Closed Hashing: Quadratic Probing, Double Hashing, and Analysis CIT594



Last Time: Closed Hashing

Closed Hashing

- A hash system where all records are stored in slots inside the hash table
- Implementations:
 - Closed hashing with buckets
 - Closed hashing with no buckets

Closed Hashing with No Buckets

Collision Resolution Policy

- The process of finding the proper position in a hash table that contains the desired record
- Used if the hash function did not return the correct position for that record due to a collision with another record
- Mainly used in closed hashing systems with no buckets
- A good collision should ensure that **empty slots** in the table **have** an **equal probability of receiving the next record inserted**

Collision Resolution

- Goal: find a free slot in the hash table when the home position for the record is already occupied
- Uses a probe function

Collision Resolution

- Probe function: function used by a *collision resolution* method to calculate where to look next in the *hash table*
- Probe sequence: the series of *slots* visited by the *probe_function* during *collision resolution*.

We will use:

- Hash function: simple mod (%)
- Slot = key % array_size

Collision Resolution

- 1. Find home slot
 - o int pos = home = h(K); where h is the hash function and K is the
 key
- 2. Probe sequence (iterative process)

Initialize i at 1

Probe function

- Increment i until the slot at pos is empty
- The probe function returns an offset from the original home position

Collision Resolution Policies

- Linear probing
- Linear probing by steps
- Pseudo-random probing
- Quadratic probing
- Double hashing

- Eliminates primary clustering
- Probe function is *quadratic*.
- Probe function:

• $p(k, i) = c_1 i^2 + c_2 i + c_3$

• Simplest form:

• $p(k, i) = i^2$

• Probe sequence: the i^{th} value is: $h(K) + i^2$

• Problem: not all slots visited by the "simplest form" probe function



If a value hashes to slot 5. Only the slots in yellow will be visited

- Solution:
 - Length of hash table: power of 2
 - probe function: $p(k, i) = (i^2 + i)/2$

All slots will be visited by the probe function

• Given a hash table of length 8, if a value hashes to slot 0, the probe sequence will be: **1**, **3**, **6**, **2**, **7**, **5**, **4**

- Google SparseHash Tables (<u>https://github.com/sparsehash/sparsehash</u>)
- Facebook Haystack (photo storage system) uses Google SparseHash Tables (<u>https://engineering.fb.com/core-data/needle-in-a-haystack-efficient-storage-of-billions-of-photos/</u>)

Secondary Clustering

- Pseudo-random probing and quadratic probing ignore the key when computing the probe sequence
- Two records with the same home slot will share the same probe sequence
- Secondary Clustering results from the keys hashing to the same slot of the table sharing the same probe sequence

- Eliminates secondary clustering
- Probe function uses the original key
- Probe function: $p(k, i) = i * h_2(k)$
- h₂ is a second hash function

- Implementation 1:
 - select *M* to be a prime number
 - $h_2(k)=1+(k \% (M-1))$
 - $p(k, i) = i * h_2(k)$

• Example:

M = 11

A record with key = 0 will generate the probe sequence: 1, 2, 3, 4, 5, 6, 7, 8, 9, 10

A record with key = 11 will generate the probe sequence: 2, 4, 6, 8, 10, 1, 3, 5, 7, 9

- Implementation 2:
 - select *M* to be a power of two
 - \circ **h**₂ returns an odd number
 - $h_2(k) = (((k/M) % (M/2))*2)+1$
 - o p(k, i) = i * h2(k)

• Example:

M = 16

A record with key = 0 will generate the probe sequence: 1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11, 12, 13, 14, 15

A record with key = 16 will generate the probe sequence: 3, 6, 9, 12, 15, 2, 5, 8, 11, 14, 1, 4, 7, 10, 13

Deletion

Deletion

- Challenges:
 - Empty slots should not stop the probe sequence when searching
 - The freed slot should be available to a future insertion

Deletion

- A tombstone is used to mark a *slot* in the *hash table* where a record has been deleted.
- **Searching**: if a tombstone is encountered, the probe sequence continues
- **Insertion**: if a tombstone is encountered, that slot is used to store the new record.
- The insertion procedure must check for duplicates



Analysis of Closed Hashing

- Assuming that every slot in the table has equal probability of being the home slot for the next record
- The probability of finding the home position is N/M (load factor α)
- The expected number of probes is:

$$1 + \sum_{i=1}^{\infty} (N/M)^{i} = 1/(1 - \alpha).$$

• The cost is a function of the load factor

Analysis of Closed Hashing

- Horizontal axis is the value for $\boldsymbol{\alpha}$
- Vertical axis is the expected number of accesses to the hash table
- Dashed lines show the cost for linear probing
- Solid lines show the cost for "random" probing (a theoretical lower bound)



Plot showing the growth rate of the cost for insertion and deletion into a hash table as the load factor.

Analysis of Closed Hashing

- For small values of α, the expected cost is low. It remains below two until the hash table is about half full
- **Rule of thumb:** design a hashing system so that the hash table never gets above about half full
- Select the table size accordingly



Plot showing the growth rate of the cost for insertion and deletion into a hash table as the load factor.