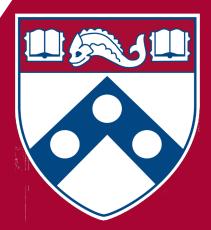
Closed Hashing: Linear Probing, Linear Probing by **Steps, and Pseudo-Random Probing** CIT594



Closed Hashing

Closed Hashing

- A hash system where all records are stored in slots inside the hash table
- Implementations:
 - Closed hashing with buckets
 - Closed hashing with no buckets

Closed Hashing with No Buckets

Collision Resolution Policy

- The process of finding the proper position in a hash table that contains the desired record
- Used if the hash function did not return the correct position for that record due to a collision with another record
- Mainly used in closed hashing systems with no buckets
- A good collision should ensure that **empty slots** in the table **have** an **equal probability of receiving the next record inserted**

Collision Resolution

- Goal: find a free slot in the hash table when the home position for the record is already occupied
- Uses a probe function

Collision Resolution

- Probe function: function used by a *collision resolution* method to calculate where to look next in the *hash table*
- Probe sequence: the series of *slots* visited by the *probe_function* during *collision resolution*.

We will use:

- Hash function: simple mod (%)
- Slot = key % array_size

Collision Resolution

- 1. Find home slot
 - o int pos = home = h(K); where h is the hash function and K is the
 key
- 2. Probe sequence (iterative process)

Initialize i at 1

Probe function

- Increment i until the slot at pos is empty
- The probe function returns an offset from the original home position

Collision Resolution Policies

- Linear probing
- Linear probing by steps
- Pseudo-random probing
- Quadratic probing
- Double hashing

Linear Probing

Linear Probing

- Works by moving sequentially through the hash table from the home slot.
- Probe function:

o p(k, i) = i

If home slot is home, the probe sequence will be home + 1, home + 2, home + 3, ... home + (M - 1)

Example

- Hash function: simple mod (%)
- M = 10
- home= key % M
- p(key, i) = i
- pos = (home + i) % M;
- Keys = [9877, 9050, 2037, 1059, 7200, 3348]

Primary Clustering

- The tendency in certain collision resolution methods to create clustering in sections of the hash table
- Happens when a group of keys follow the same probe sequence during collision resolution
- primary clustering lead to empty slots in the table to not have an equal probability of receiving the next record inserted

Primary Clustering

- Linear probing leads to primary clustering
- Linear probing is one of the worst collision resolution methods

Linear Probing by Steps

Linear Probing by Steps

- Goal: avoid primary clustering / improve linear probing
- Idea: skip slots by some constant *C* other than 1
- Probe function:

• p(k, i) = c * i

• **c must be relatively prime to** *M* to generate a linear probing sequence that visits all slots in the table

Example

- Hash function: simple mod (%)
- M = 10
- home= key % M
- c = 3
- p(key, i) = c * i
- pos = (home + 3i) % M;
- Keys = [9877, 9050, 2037, 1059, 7200, 3348]

Pseudo-Random Probing

Pseudo-Random probing

- Idea: select the next position on the probe sequence at random from the unvisited slots
- The random sequence should be the same for insertion and searching (impossible for a truly random sequence)

Pseudo-Random probing

- Stores a random permutation of the values 1 through the size of the *hash table*
- The term *i* of the *probe sequence* is the value of position *i* in the permutation array

Pseudo-Random probing

- Probe function:
 - o p(k, i) = Permutation[i]
- Permutation:
 - Array of length *M*
 - Stores a value of 0 in position **Permutation[0]**
 - Stores a random permutation of the values from 1 to M-1 in slots 1 to M-1.

Example

- Hash function: simple mod (%)
- M = 10
- home = key % M
- Permutation = [0, 3, 7, 6, 1, 4, 9, 2, 5, 8]
- p(key, i) = Permutation[i]
- pos = (home + Permutation[i]) % M;
- Keys = [157, 273, 17, 913, 110, 258]