



CIS1921



Lecture 7:

Concluding Mixed-Integer
Programming

Reminders



- HW3 release tonight or tomorrow depending on how I'm feeling
- HW3 due March 18
- Next class
- Following week spring break
- Week after that – super special lecture.

CPU Job Assignment Problem



- There are n jobs that must be completed
- There are m CPUs available to do the jobs
 - Each CPU can do at most one job, hence $m \geq n$
- There is a cost associated with running a particular job on a particular CPU
- How to assign jobs to CPUs, minimizing total cost?

Variables



$$x_{c,j} = \begin{cases} 1 & \text{if CPU } c \text{ gets job } j \\ 0 & \text{else} \end{cases}$$

```
for c in range(num_cpus):
    for j in range(num_jobs):
        x[c, j] = model.IntVar(0, 1, f'cpu {c} gets job {j}')
```

Constraint



- Each CPU gets at most 1 job

$$\text{For each CPU } c, \sum_{j \in \text{jobs}} x_{c,j} \leq 1$$

```
# Each cpu gets at most one job
for c in range(num_cpus):
    model.Add(
        sum(x[c, j] for j in range(num_jobs)) <= 1
    )
```

Constraint



- Each Job gets exactly one CPU

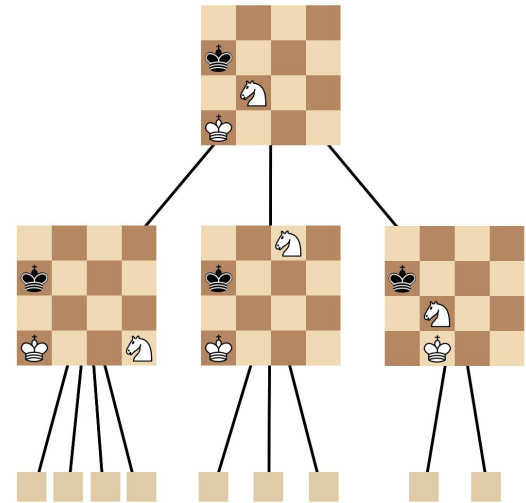
For a job j^* , over all CPUs, exactly one of $x_{c_1, j^*}, x_{c_2, j^*}, \dots, x_{c_n, j^*}$ equals 1

```
# Each job gets exactly one CPU
for j in range(num_jobs):
    model.Add(
        sum(x[c, j] for c in range(num_cpus)) == 1
    )
```

How do MIP solvers work?



- Most fundamental technique: **branch and bound**
 - Chess engines work using branch and bound too ("alpha-beta pruning")
- For simplicity, let's assume that all integer variables have lower and upper bounds
 - $lb(x) \leq x \leq ub(x)$



Naive Branching



- Want to solve MIP P where integer variables are bounded
- What's a first step for tree traversal of the search space?
- **Idea:** split the domain of a variable in half
 - Generates subproblems which can be solved recursively
- Pick whichever subproblem has the higher objective value, and discard infeasible solutions

Naive Branching (Pseudocode)

find the optimal objective value for P

naive(P):

if lb = ub for all vars:

if P violates a constraint:

return **INFEASIBLE** (-inf)

return **objective_value**(P)

let x be a variable with $\text{lb}(x) < \text{ub}(x)$

let $m = \lfloor (\text{lb}(x) + \text{ub}(x)) / 2 \rfloor$

return **max**{**naive**($P|x \leq m$), **naive**($P|x \geq m$) }



How bad is Naive Branching?

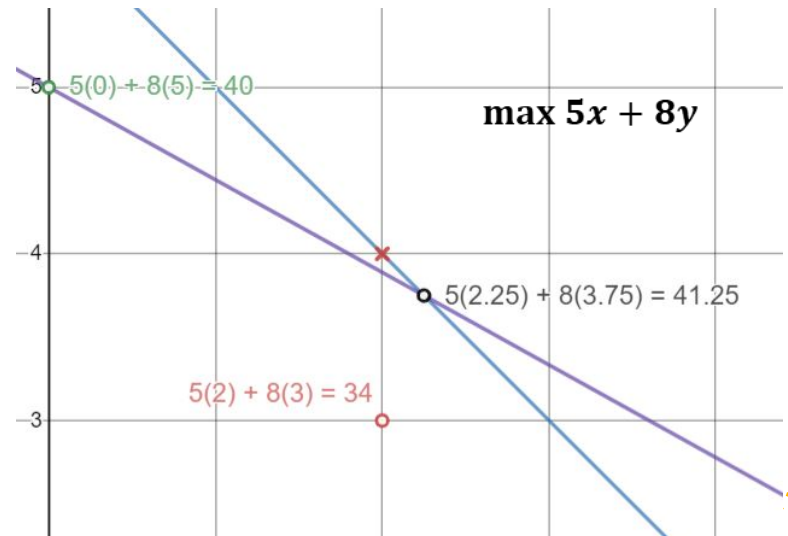


- Does naive branching even terminate?
 - Only for pure integer programs!
- Which assignments does the algorithm discard or visit?
 - Need to evaluate both branches -- visits all feasible solutions!
- Basically the same as brute force
- Runtime scales with size of search space

Recall: LP Relaxation



- For a MIP P , we get its **LP relaxation** $LP(P)$ by allowing all variables to be fractional
 - Can't just round LP solution
- **Key observation:** the LP solution is always at least as good as the MIP solution (by objective value)
- Corollary: if all integer vars take integer values in optimal solution to $LP(P)$, then it is also optimal solution to P



Adding Inference



- **Idea:** since LP is polytime-solvable, use LP solver as inference engine!
- Instead of recursing until all variables have one value, solve $LP(P)$ and check whether all integer variables have integer values
- Branch on integer variable x whose value v is fractional in $LP(P)$
 - Create subproblems $x \leq \lfloor v \rfloor$ and $x \geq \lceil v \rceil$

Pruning Fruitless Nodes



- **Idea:** discard partial solutions that will never yield a better objective value than one we've already found
- If we've seen a MIP solution with a better objective value than $LP(P)$, discard P since any integer solution can only be worse



Branch & Bound



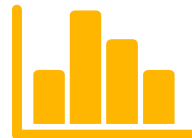
- First version developed by Ailsa Land and Alison Harcourt in 1960
- Combines branching of solution space with bounds-based pruning
- B&B is an **algorithm paradigm**: a “meta-algorithm” that can be used to design algorithms for many different optimization algorithms



Branch & Bound

(Recursive)

```
# find the optimal objective value for  $P$ 
# best_seen is the best objective value so far
branch_and_bound( $P$ , best_seen =  $-\text{inf}$ ):
    let LP_soln = solve_LP(LP( $P$ ))
    if LP_soln = INFEASIBLE: return INFEASIBLE
    if objective_value(LP_soln)  $\leq$  best_seen:
        return  $-\text{inf}$ 
    if LP_soln satisfies integrality constraints of  $P$ :
        return objective_value(LP_soln)
    let  $x$  be an int var with fractional value  $v$  in LP_soln
    let obj1 = branch_and_bound( $P|x \leq \lfloor v \rfloor$ , best_seen)
    set best_seen = max{obj1, best_seen}
    let obj2 = branch_and_bound( $P|x \geq \lceil v \rceil$ , best_seen)
    return max{obj1, obj2}
```

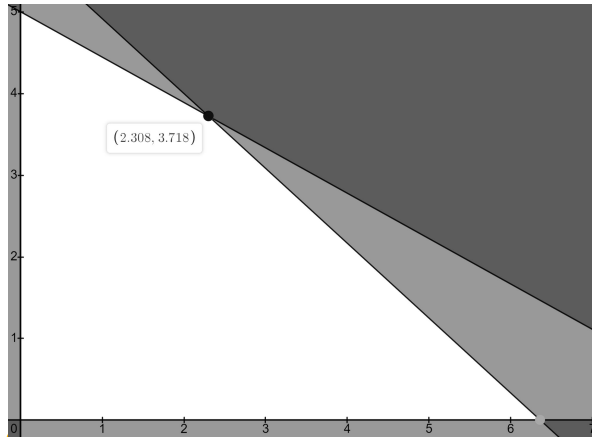


Example: Branch & Bound



$$\begin{aligned} \max \quad & f(x, y) = 5x + 8y \\ \text{s.t.} \quad & 5x + 9y \leq 45 \\ & 1.1x + 1.2y \leq 7 \\ & x, y \in [0..100] \end{aligned}$$

$$\begin{aligned} f(2.31, 3.72) \\ = 41.28 \end{aligned}$$



Example: Branch & Bound

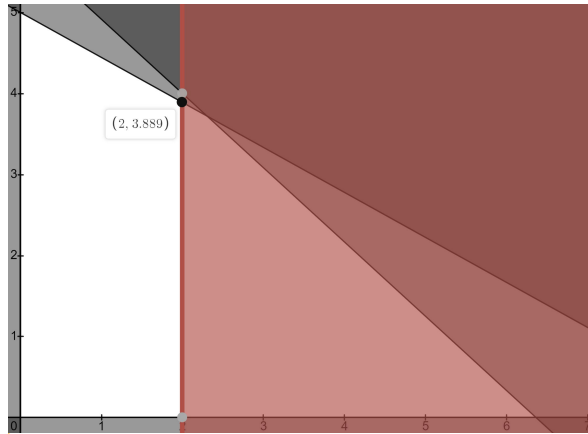


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$$x \leq 2$$

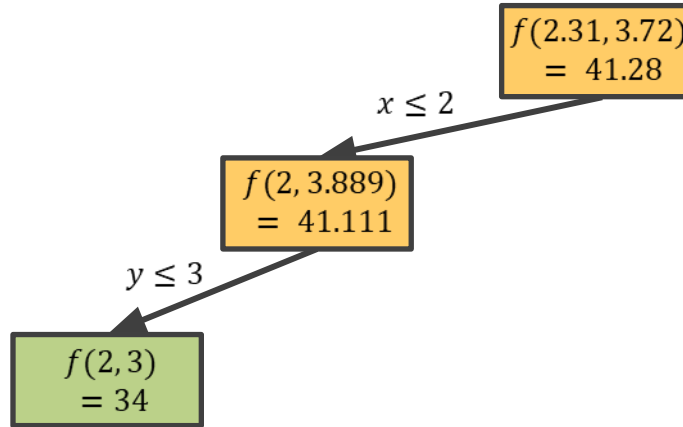
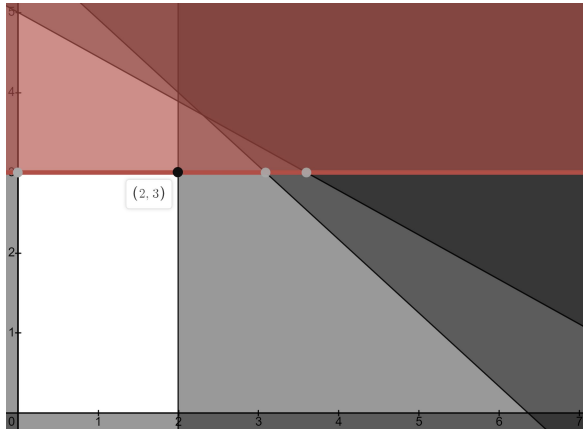
$$\begin{aligned} f(2, 3.889) \\ = 41.111 \end{aligned}$$



Example: Branch & Bound



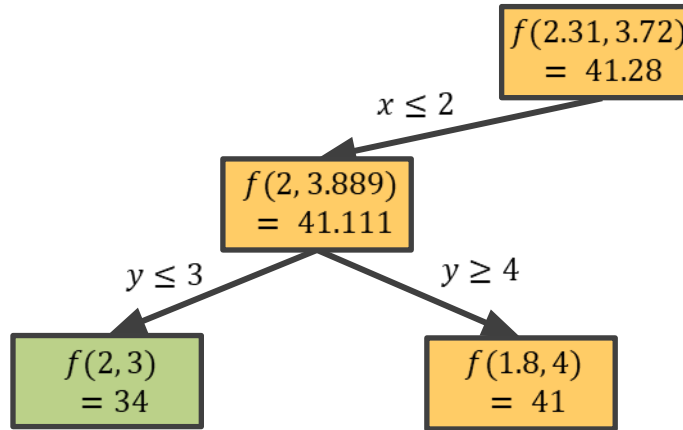
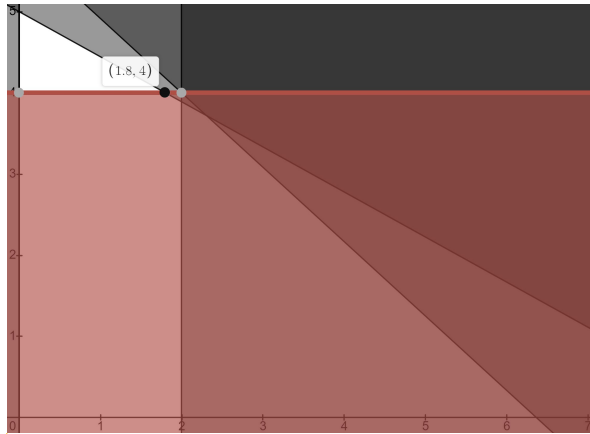
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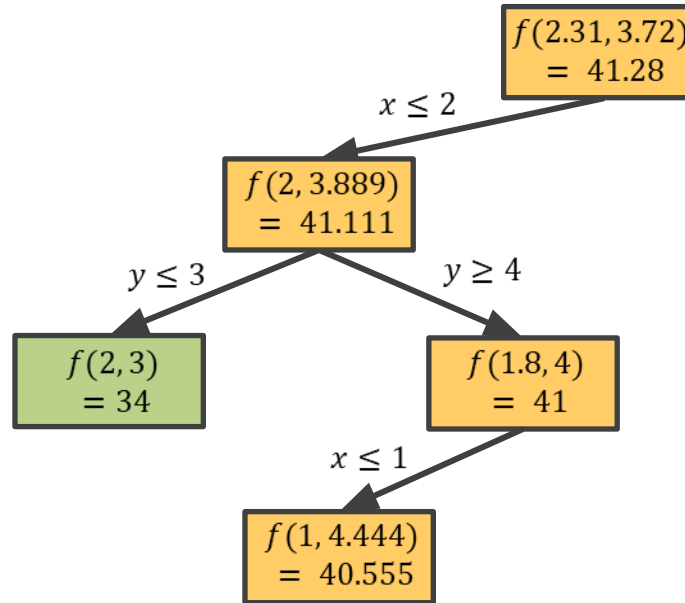
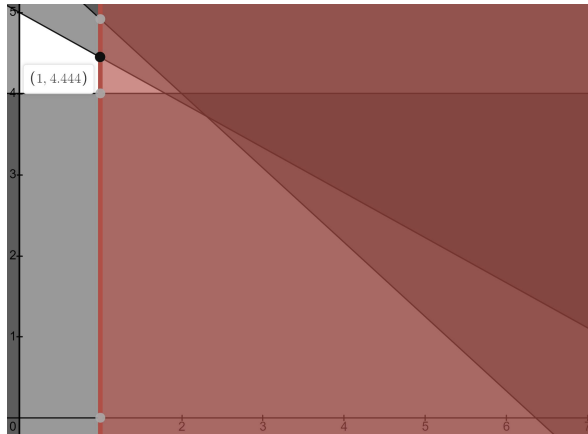
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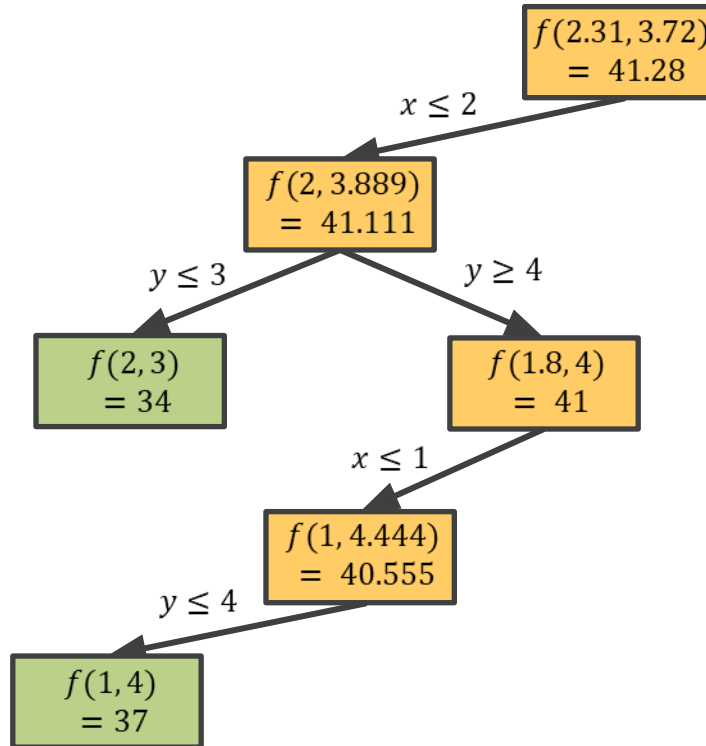
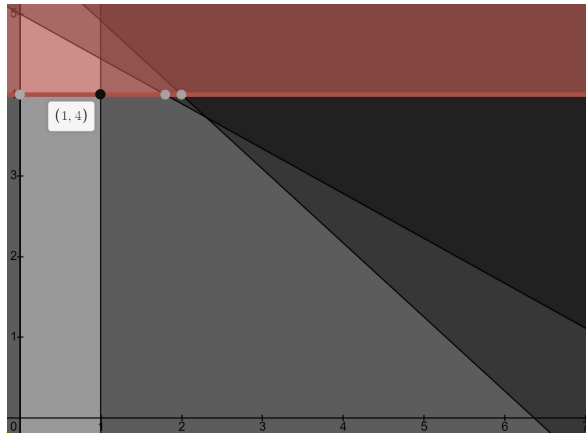
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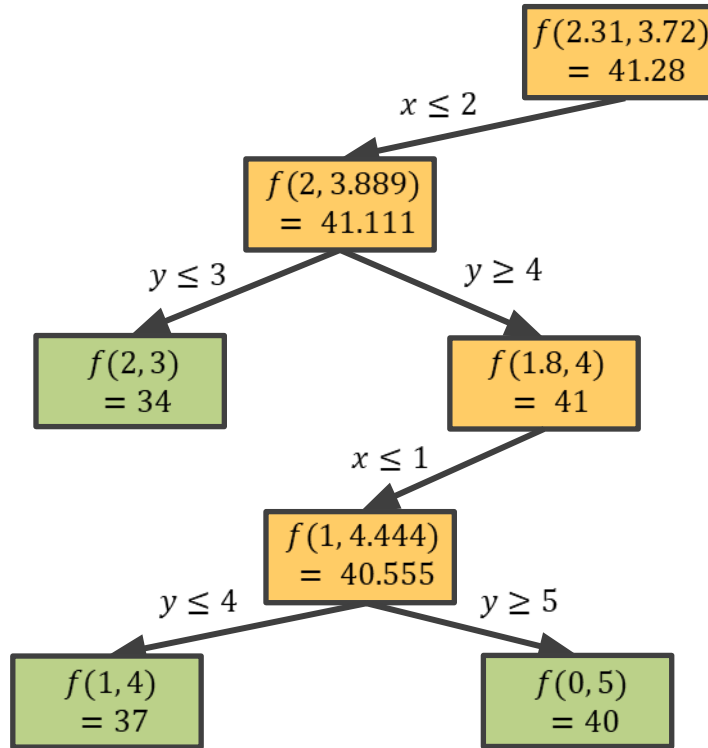
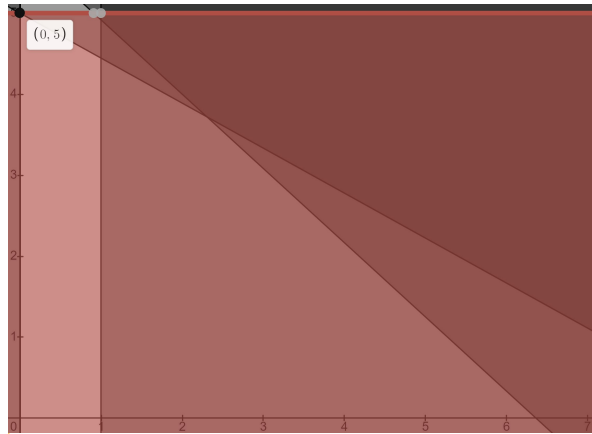
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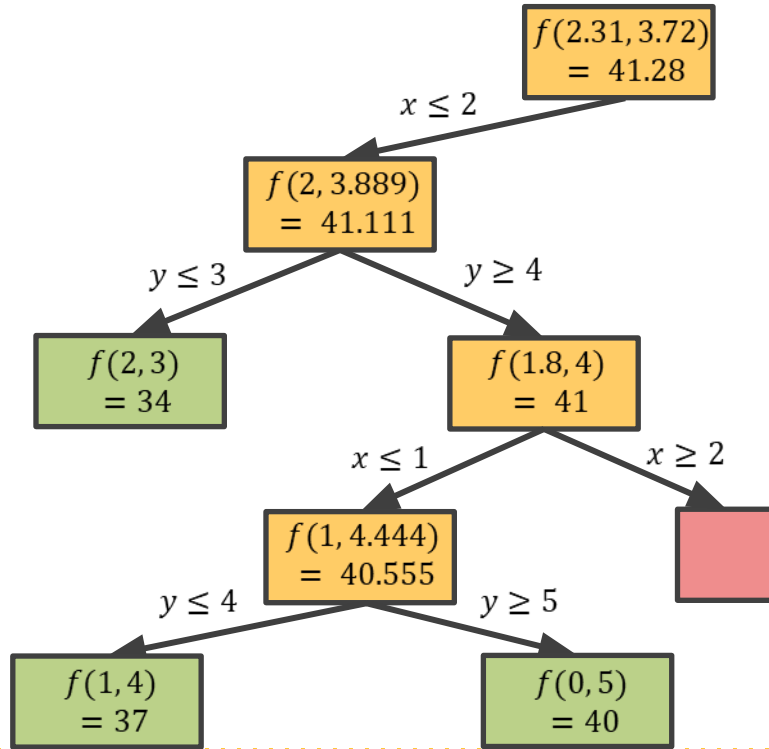
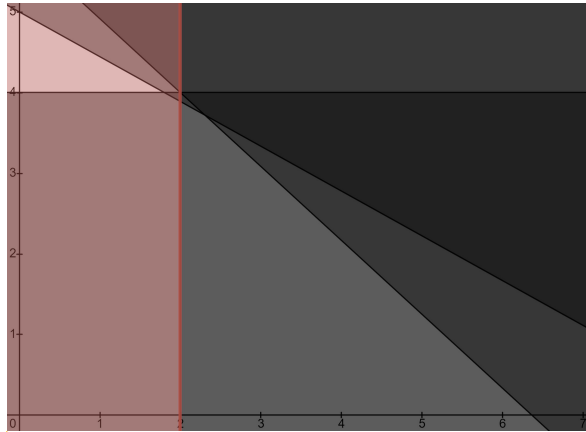
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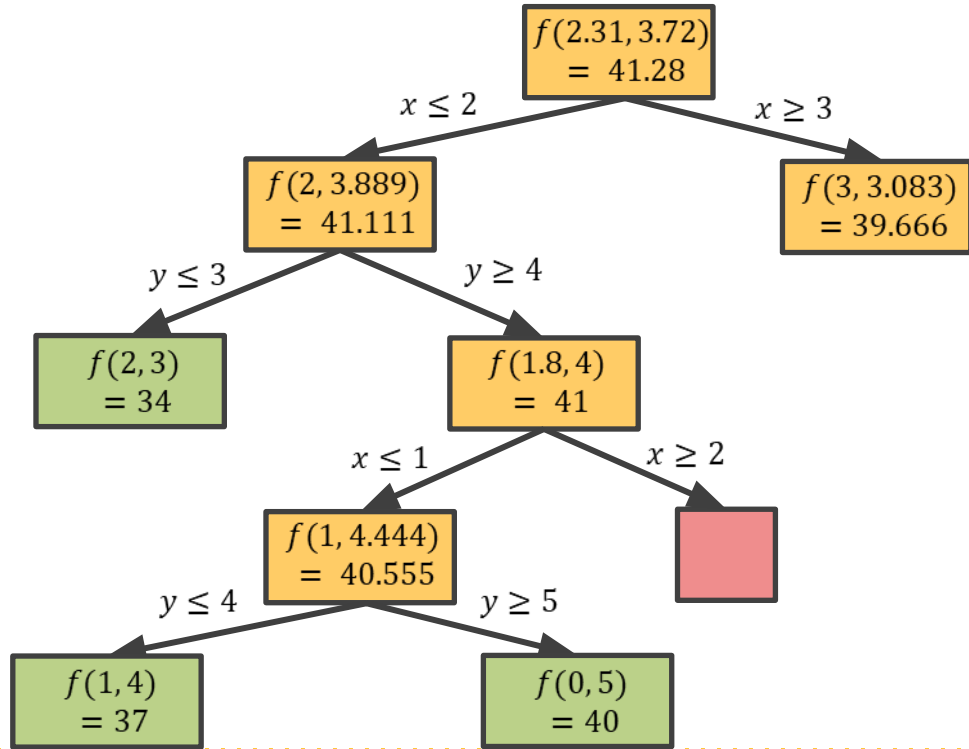
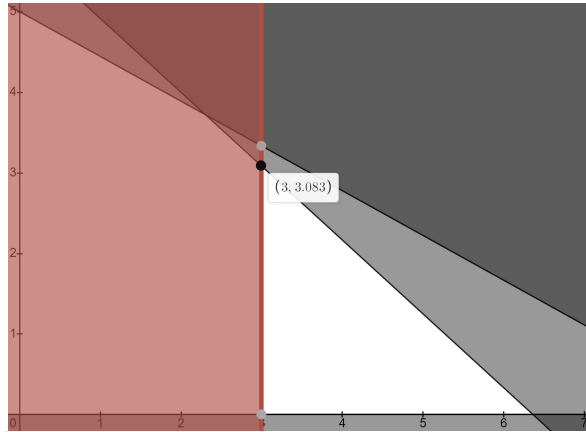
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Example: Branch & Bound



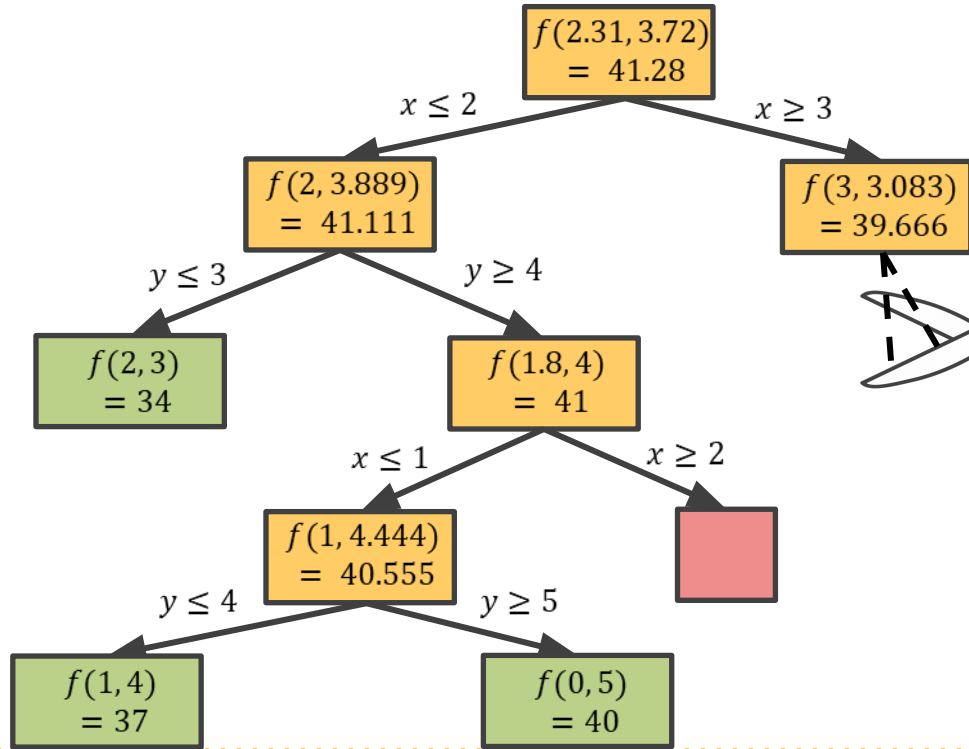
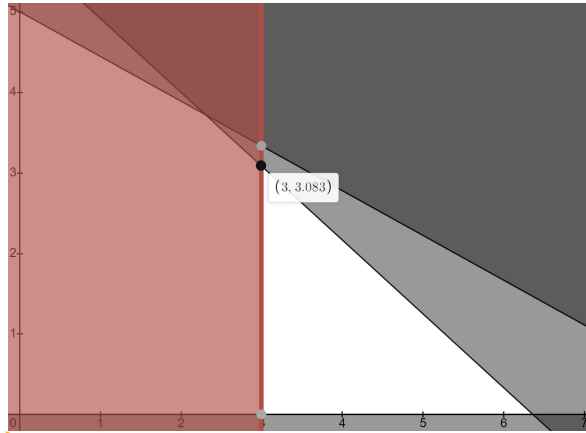
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Example: Branch & Bound



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Iterative Branch & Bound



```
# find the optimal objective value for  $P_0$ 
branch_and_bound( $P_0$ ):
    let best_seen = -inf
    let subproblems_to_visit = { $P_0$ }
    while to_visit is nonempty:
        let  $P$  = subproblems_to_visit.pop()
        let LP_soln = solve_LP(LP( $P$ ))
        if LP_soln = INFEASIBLE: continue
        if objective_value(LP_soln)  $\leq$  best_seen: continue
        if LP_soln satisfies integrality constraints for  $P$ :
            set best_seen = objective_value(LP_soln)
            continue
        let  $x$  be an int var with fractional value  $v$  in LP_soln
        subproblems_to_visit.add(branch_and_bound( $P | x \leq \lfloor v \rfloor$ ))
        subproblems_to_visit.add(branch_and_bound( $P | x \geq \lceil v \rceil$ ))
    return best_seen
```

Tuning Branch & Bound

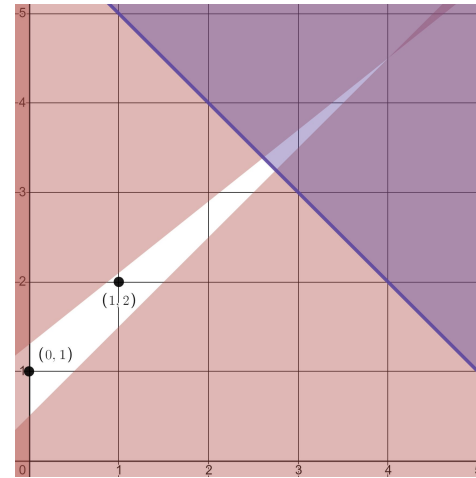
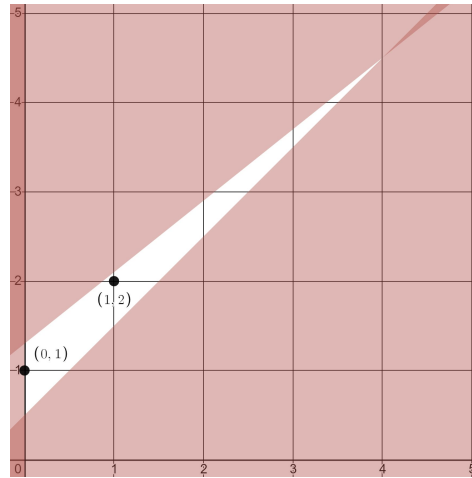


- What choices can we make when implementing branch and bound?
- Which subproblem to visit next?
 - Visit first-added subproblem (BFS)
 - Visit last-added subproblem (DFS)
 - Visit subproblem with best LP objective (“best-first search”)
- Which variable to branch on?
 - Most constrained variable (smallest domain, e.g. booleans)
 - Largest/smallest coefficient in objective function
 - Closest/farthest to halfway between integers (e.g. value of 0.5)
- Most solvers allow user to tune these based on knowledge of problem

Improving B&B with Cuts



- Informally, a **cut** for a MIP P is a new constraint (inequality) that doesn't eliminate any feasible solutions for P , but does for $LP(P)$
 - Tighter LP relaxation means we converge faster to MIP solution!



Branch & Cut



- If we can find cuts of MIP, then add them and recurse on new MIP!
 - How to find cuts? Out of scope – method based on simplex algorithm
- Otherwise, branch to create subproblems as before
- Proposed by Manfred Padberg and Giovanni Rinaldi in 1989



The Knapsack Problem



- Given n items with values v_1, \dots, v_n and weights w_1, \dots, w_n , select maximum-value subset to fit into a knapsack with capacity W .



0.5 oz., \$500



Max Weight: 400 oz.



100 oz., \$2,000



300 oz., \$4,000



1 oz., \$5,000



200 oz., \$5,000

Fractional Knapsack



- What if items are subdivisible? Want to decide how much of each item to take (as a fraction from 0 to 1).
- Intuitively, do we want to prioritize... most valuable items? Lightest items? Something else?
- **Greedy algorithm:** Sort items by value-to-weight ratio. Take as much of each item as possible, in order, until knapsack is full.

0/1 Knapsack



- In the 0/1 knapsack problem, we either select an item or we don't.
- Does greedy algorithm still work?
 - No: 0/1 knapsack is NP-complete!



MIP for 0/1 Knapsack



- MIP formulation is very straightforward:

$$\text{maximize } \sum_{i=1}^n x_i v_i$$

$$\text{subject to } \sum_{i=1}^n x_i w_i \leq W$$

- Why use MIP instead of...
 - $O(nW)$ dynamic programming algorithm
 - $O(n \lg n)$ approximation algorithm (at least 50% of optimal)

B&B for Knapsack



- How can we use branch and bound as an **algorithm paradigm** for the 0/1 knapsack problem (without using MIP)?

```
b&b_knapsack(items, W, best_seen):  
  let fractional_soln = greedy_fractional(items, W)  
  if value(fractional_soln) ≤ best_seen:  
    return -inf  
  if fractional_soln has no fractionally-selected items:  
    return value(fractional_soln)  
  let x be a fractionally-selected item in fractional_soln  
  let obj1 = b&b_knapsack(items - {x}, W, best_seen)  
  set best_seen = max{obj1, best_seen}  
  let obj2 = v(x) + b&b_knapsack(items - {x}, W - w(x), best_seen - v(x))  
  return max{obj1, obj2}
```