

\bar{x} \bar{x} \bar{x} CIS1921



Lecture 3: Algorithms for SAT

Reminders



- Homework 0 was due on Monday
- Homework 1 due Monday, Feb 10, 11:59PM
- OH schedule:
 - Thomas: Sunday 3-4pm
 - Cindy: Tuesday 8-9pm
 - Ishaan: Wednesday 9:30-10:30pm
 - All OH held on OHQ

Grading



- Homework: 44%
- Final Project: 38%
- Quizzes: 10%
- Attendance: 8%



Academic Integrity



- Work on assignments individually (except final project)
 - Discussion encouraged, but work should be yours
- OK: high-level discussions
 - “Can you help me understand the DPLL algorithm?”
- OK: low-level discussions
 - “How do I time my program in OR-Tools?”
- Be careful: mid-level discussions
 - Not OK: “How exactly do I write this constraint?”

Health Logistics



- If you have a reasonable suspicion that you have Covid or sickness, don't come
 - Email me before class and we'll work something out



Recap



Last week

- Using SAT solvers in Python (PycoSAT)
- Encode other problems (graph coloring) as SAT

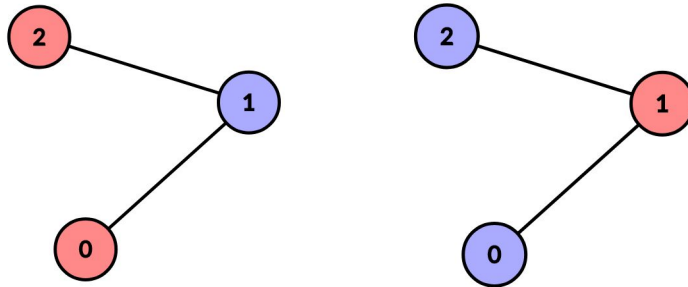
This week

- Build up an algorithm to solve SAT

Symmetry Breaking



- Solving UNSAT graph coloring problems takes a very long time... why?
- Must rule out every symmetric coloring
- Ex: equivalent colorings



Symmetry Breaking



- Key idea: add constraints that rule out equivalent symmetric colorings
- Basic way to do this: pick some vertices (ideally a dense subgraph) and fix their colors

DEMO Part 2

Encoding Stable Matchings



We have n men and n women. Each man and woman submits a preference list ranking everyone of the opposite sex (descending).

Goal: find a **matching** of men to women.

A man and woman who both prefer each other to their matched partners are a **blocking pair**.

A matching is **stable** if it has no blocking pairs.

Encoding Stable Matchings



m_{ip} : if man i is matched to p^{th} woman or later on his list

w_{ip} : if woman i is matched to p^{th} man or later on her list

$[W_1 > W_2] M_1 \longleftrightarrow W_1 [M_1 > M_2]$

$[W_1 > W_2] M_2 \longleftrightarrow W_2 [M_1 > M_2]$

$m_{1,1}$	$m_{1,2}$	$m_{2,1}$	$m_{2,2}$	$w_{1,1}$	$w_{1,2}$	$w_{2,1}$	$w_{2,2}$
T	F	T	T	T	F	T	T

Encoding Stable Matchings



m_{ip} : if man i is matched to p^{th} woman or later on his list

w_{ip} : if woman i is matched to p^{th} man or later on her list

- **C1**: every man is matched

$$\{m_{i1} \mid 1 \leq i \leq n\}$$

(plus symmetric constraints for women for this and the following constraints)

Encoding Stable Matchings



m_{ip} : if man i is matched to p^{th} woman or later on his list

w_{ip} : if woman i is matched to p^{th} man or later on her list

- **C2:** if a man gets his p^{th} or later choice, it's also his $(p - 1)^{\text{th}}$ or later choice

$$\{m_{ip} \Rightarrow m_{i(p-1)} \mid 1 \leq i \leq n, 2 \leq p \leq n\}$$

Encoding Stable Matchings



m_{ip} : if man i is matched to p^{th} woman or later on his list

w_{ip} : if woman i is matched to p^{th} man or later on her list

- **C3**: if man i is matched to woman j , then she is matched to him also

$$\{m_{ip} \wedge \overline{m_{i(p+1)}} \Rightarrow w_{jq} \wedge \overline{w_{j(q+1)}} \mid 1 \leq i, j \leq n\}$$

- p = position of woman j in man i 's list
- q = position of man i in woman j 's list

Encoding Stable Matchings



m_{ip} : if man i is matched to p^{th} woman or later on his list

w_{ip} : if woman i is matched to p^{th} man or later on her list

- **C4:** if man i is matched to someone worse than woman j , her match must be better than him

$$\{m_{i(p+1)} \Rightarrow \overline{w_{jq}} \mid 1 \leq i, j \leq n\}$$

- p = position of woman j in man i 's list
- q = position of man i in woman j 's list

Why Stable Matchings?



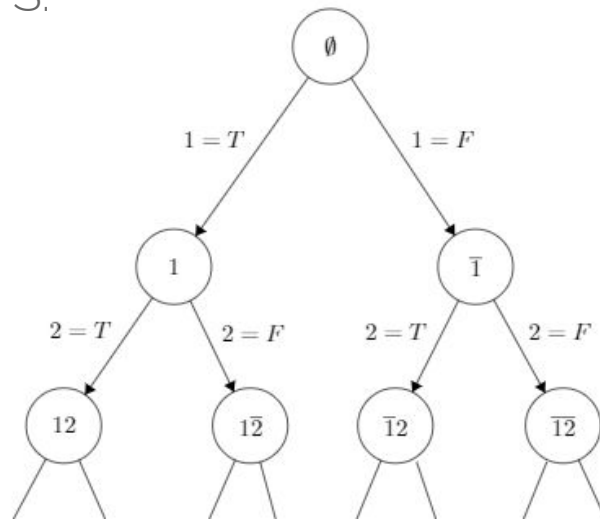
- Gale-Shapley algorithm solves SM problem in linear time. Why use SAT solvers?
- SMTI: stable matching problem where preference lists may be incomplete and contain ties
- SM-C: stable matching problem with couples
- Our encoding easily generalizes to SMTI, SM-C
- Theorem: SMTI and SM-C are NP-complete.

SAT is Hard!



Naive Search for SAT

- Naive algorithm: try every possible assignment until we find a satisfying assignment or exhaust the search space
- Can interpret this as a DFS:
(search tree)



Overarching Class Themes

- Accept the fact that the problems we will look at are very hard and “exponential runtime”
 - Take solace in the fact that for many inputs, the problem won’t take exponential time
- Every speed-up counts
 - *Take careful consideration of the balance between runtime and complexity*
- There will never be a “right answer”
 - Often, the best thing to do for a problem depends on the problem itself and its data!



Simplify the Search Space

Find a *minimal satisfying assignment* for the following formula:

$$\varphi = (x_1 \vee \overline{x_2} \vee \overline{x_3}) \wedge (\overline{x_2} \vee x_4) \wedge (\overline{x_1} \vee x_3 \vee x_5) \wedge (\overline{x_2} \vee \overline{x_1}) \wedge (\overline{x_2} \vee x_6 \vee x_7)$$

Find a *minimal satisfying assignment* for the following formula:

$$\varphi = (x_1 \vee \overline{x_2} \vee \overline{x_3}) \wedge (\overline{x_2} \vee x_4) \wedge (\overline{x_1} \vee x_3 \vee x_5) \wedge (\overline{x_2} \vee \overline{x_1}) \wedge (\overline{x_2} \vee x_6 \vee x_7)$$

$$x_2 = \text{FALSE} \quad x_3 = \text{TRUE}$$

Trimming the Search Space



- If a formula is satisfiable (has a satisfying assignment to variables), then in the assignment, each clause must individually evaluate to TRUE.

$$\varphi = C_1 \wedge C_2 \wedge \dots \wedge C_n$$

Trimming the Search Space



- When we set $x = T$, what happens to the clauses containing x ?
- **Observation 1:** Any clause containing the positive literal x becomes satisfied, so we no longer need to consider those clauses
 - In logic: $(T \vee 1 \vee 2 \vee \dots) = T$
 - Significance: we should remove all clauses containing x

Trimming the Search Space



- When we set $x = T$, what happens to the clauses containing \bar{x} ?
- **Observation 2:** Any clause containing the negative literal \bar{x} needs to be satisfied by a different literal, so we can ignore \bar{x} in that clause
 - In logic: $(F \vee 1 \vee 2 \vee \dots) = (1 \vee 2 \vee \dots)$
 - Significance: we should remove \bar{x} from all clauses containing it



**We are honing in on
whatever is left that is
unassigned and not yet
evaluated to *TRUE*.**

The Splitting Rule



- The previous observations are called the **splitting rule**
- After repeatedly applying the splitting rule to formula φ :
 - If there are **no clauses left**, then all clauses have been satisfied, so φ is satisfied
 - $\varphi = \emptyset$ denotes that there are no clauses left
 - If φ ever contains an **empty clause**, then all literals in that clause are False, so we made a mistake
 - ϵ denotes the empty clause
 - $\epsilon \in \varphi$ denotes that φ contains an empty clause



The Splitting Rule

- The splitting rule allows us to create a smarter recursive **backtracking** algorithm
- Backtracking: repeatedly make a guess to explore partial solutions, and if we hit “dead end” (contradiction) then undo the last guess

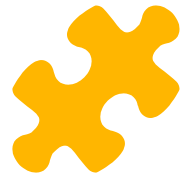
```
seansz: ~/Desktop/cs106b
Searching...
#####
#@# # # #
# # # # #
# ### # # #
# # # #
# ##### #####
# # e#
#####
```



Backtracking Notation

- For a CNF φ and a literal x , define $\varphi|x$ (“ φ given x ”) to be a new CNF produced by:
 - Removing all clauses containing x
 - Removing \bar{x} from all clauses containing it
- Conditioning is “commutative”: $\varphi|x_1|x_2 = \varphi|x_2|x_1$

Backtracking (Pseudocode)



```
# check if  $\varphi$  is satisfiable
```

```
backtrack( $\varphi$ ):
```

```
  if  $\varphi = \emptyset$ : return True
```

```
  if  $\epsilon \in \varphi$ : return False
```

```
  let  $x = \text{pick\_variable}(\varphi)$ 
```

```
  return backtrack( $\varphi|x$ ) OR backtrack( $\varphi|\bar{x}$ )
```



Example: Backtracking

Steps

$(\bar{1} \vee \bar{2})$

$(\bar{1} \vee 2 \vee \bar{3})$

$(3 \vee \bar{4} \vee \bar{5})$

$(3 \vee 4 \vee \bar{5})$

1	2	3	4	5



Example: Backtracking

(**1** ∨ $\bar{2}$)

(**1** ∨ 2 ∨ $\bar{3}$)

(3 ∨ $\bar{4}$ ∨ $\bar{5}$)

(3 ∨ 4 ∨ $\bar{5}$)

Steps



1	2	3	4	5
T				



Example: Backtracking

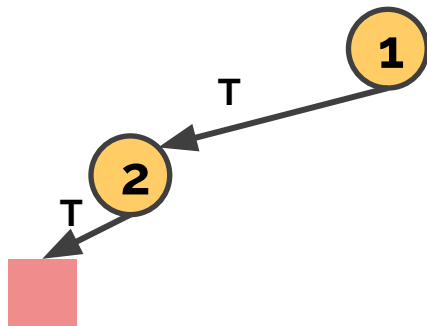
($\bar{1} \vee \bar{2}$) **Conflict!**

($\bar{1} \vee 2 \vee \bar{3}$)

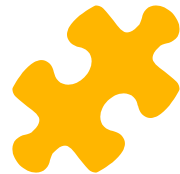
($3 \vee \bar{4} \vee \bar{5}$)

($3 \vee 4 \vee \bar{5}$)

Steps

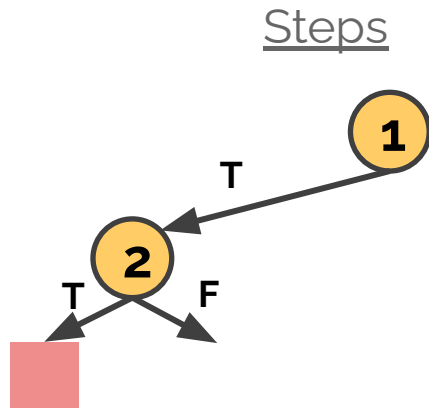


1	2	3	4	5
T	T			



Example: Backtracking

($\overline{1} \vee \overline{2}$)
($\overline{1} \vee \overline{2} \vee \overline{3}$)
($3 \vee \overline{4} \vee \overline{5}$)
($3 \vee 4 \vee \overline{5}$)



1	2	3	4	5
T	F			



Example: Backtracking

($\bar{1} \vee \bar{2}$)

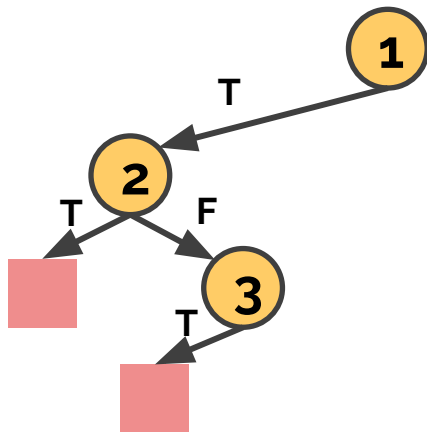
($\bar{1} \vee 2 \vee \bar{3}$) **Conflict!**

($3 \vee \bar{4} \vee \bar{5}$)

($3 \vee 4 \vee \bar{5}$)

1	2	3	4	5
T	F	T		

Steps





Example: Backtracking

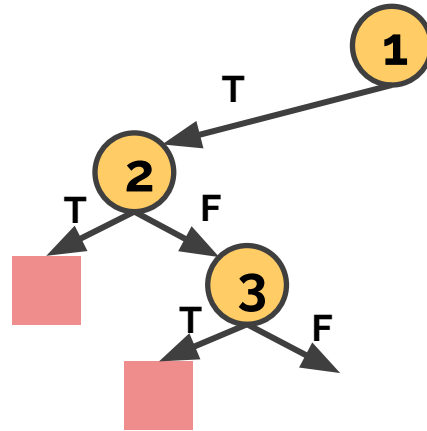
($\bar{1} \vee \bar{2}$)

($\bar{1} \vee 2 \vee \bar{3}$)

($3 \vee \bar{4} \vee \bar{5}$)

($3 \vee 4 \vee \bar{5}$)

Steps



1	2	3	4	5
T	F	F		

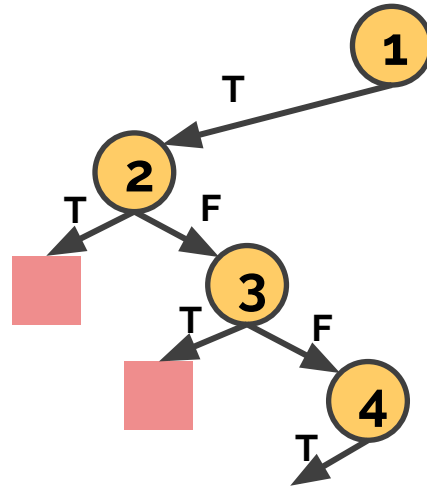


Example: Backtracking

($\bar{1} \vee \bar{2}$)
($\bar{1} \vee 2 \vee \bar{3}$)
($3 \vee \bar{4} \vee \bar{5}$)
($3 \vee 4 \vee \bar{5}$)

1	2	3	4	5
T	F	F	T	

Steps





Example: Backtracking

($\bar{1} \vee \bar{2}$)

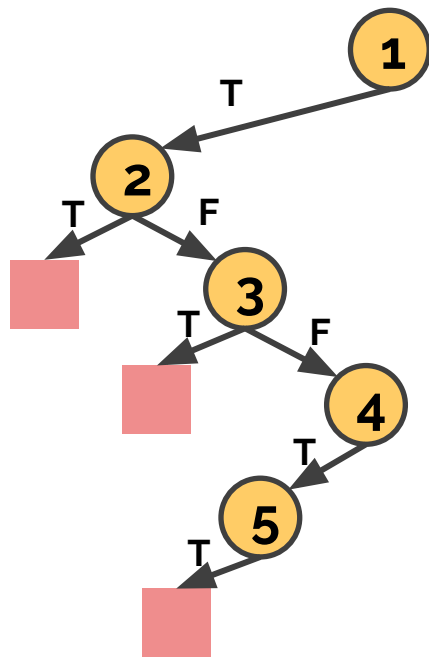
($\bar{1} \vee 2 \vee \bar{3}$)

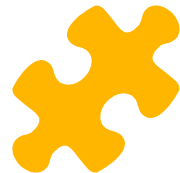
($3 \vee \bar{4} \vee \bar{5}$) **Conflict!**

($3 \vee 4 \vee \bar{5}$)

1	2	3	4	5
T	F	F	T	T

Steps



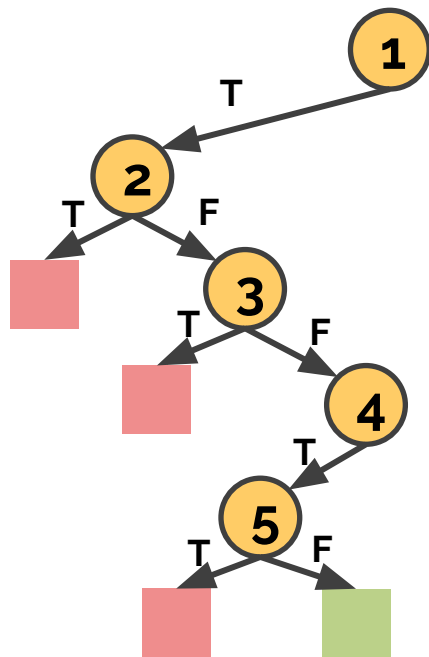


Example: Backtracking

(1 v 2)
(1 v 2 v 3)
(3 v 4 v 5)
(3 v 4 v 5)

1	2	3	4	5
T	F	F	T	F

Steps



Towards Implementation: Efficient Splitting

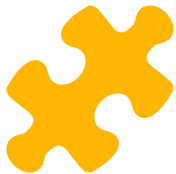


- How do we compute $\varphi|x$?
- Goals:
 - Support fast searching for empty clauses
 - Support fast backtracking
 - Fast to actually compute $\varphi|x$

Naïve Idea 1



- Transform φ into $\varphi|x$ by deleting satisfied clauses and False literals from φ
 - Deletion not too expensive if we use linked lists
 - Can quickly recognize an empty clause (linked list will be empty), but need to check all clauses
 - Big issue: how do we backtrack?



Naïve Idea 2

- Simple fix: instead of modifying φ directly, create a copy first and modify that
 - Easy backtracking – just restore the old formula
 - Big issue: too expensive (time and memory) to copy formula every time we split
 - What if we have hundreds of thousands, even millions of clauses?

Towards a smarter scheme



- Don't modify or copy the formula!
- **Key observation:** We must only backtrack once a clause has become empty *after* the Splitting Rule has been applied!



1 Watched Literal Scheme

- **Observation:** a clause can only become empty if it has just one unassigned literal remaining
 - Ideally, only need to check these clauses
- Each clause “watches” one literal and maintains **watching invariant:** the watched literal is True or unassigned
 - If the watched literal becomes False, watch another
 - If there are no more True/unassigned literals to watch, then the clause must be empty



Example: 1 Watched Literal

Steps

$$(\overline{1} \vee \overline{2})$$

$$(\overline{1} \vee 2 \vee \overline{3})$$

$$(3 \vee \overline{4} \vee \overline{5})$$

$$(3 \vee 4 \vee \overline{5})$$

1	2	3	4	5



Example: 1 Watched Literal

$$(\overline{1} \vee \overline{2})$$

$$(\overline{1} \vee 2 \vee \overline{3})$$

$$(3 \vee \overline{4} \vee \overline{5})$$

$$(3 \vee 4 \vee \overline{5})$$

Steps



1	2	3	4	5
T				



Example: 1 Watched Literal

$$(\bar{1} \vee \bar{2})$$

$$(\bar{1} \vee \bar{2} \vee \bar{3})$$

$$(\bar{3} \vee \bar{4} \vee \bar{5})$$

$$(\bar{3} \vee \bar{4} \vee \bar{5})$$

Steps



1	2	3	4	5
T				



Example: 1 Watched Literal

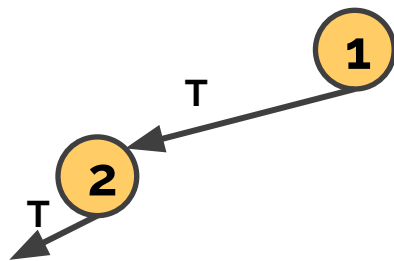
$$(\bar{1} \vee \bar{2})$$

$$(\bar{1} \vee 2 \vee \bar{3})$$

$$(3 \vee \bar{4} \vee \bar{5})$$

$$(3 \vee 4 \vee \bar{5})$$

Steps



1	2	3	4	5
T	T			



Example: 1 Watched Literal

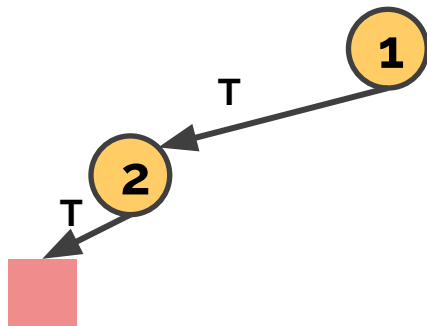
$(\bar{1} \vee \bar{2})$ **Conflict!**

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$(\bar{3} \vee \bar{4} \vee \bar{5})$

$(\bar{3} \vee \bar{4} \vee \bar{5})$

Steps



1	2	3	4	5
T	T			



Example: 1 Watched Literal

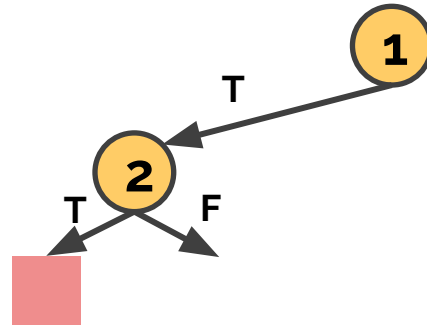
$$(\bar{1} \vee \bar{2})$$

$$(\bar{1} \vee 2 \vee \bar{3})$$

$$(3 \vee \bar{4} \vee \bar{5})$$

$$(3 \vee 4 \vee \bar{5})$$

Steps



1	2	3	4	5
T	F			



Example: 1 Watched Literal

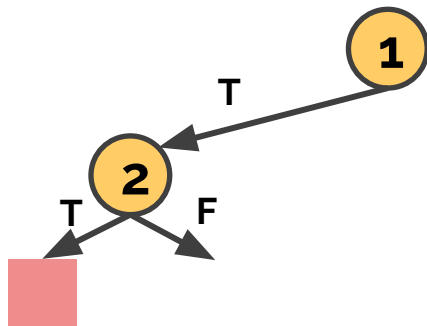
$$(\bar{1} \vee \bar{2})$$

$$(\bar{1} \vee 2 \vee \bar{3})$$

$$(3 \vee \bar{4} \vee \bar{5})$$

$$(3 \vee 4 \vee \bar{5})$$

Steps



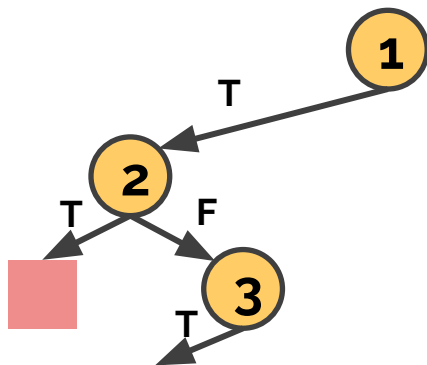
1	2	3	4	5
T	F			



Example: 1 Watched Literal

$(\bar{1} \vee \bar{2})$
 $(\bar{1} \vee 2 \vee \bar{3})$
 $(3 \vee \bar{4} \vee \bar{5})$
 $(3 \vee 4 \vee \bar{5})$

Steps



1	2	3	4	5
T	F	T		



Example: 1 Watched Literal

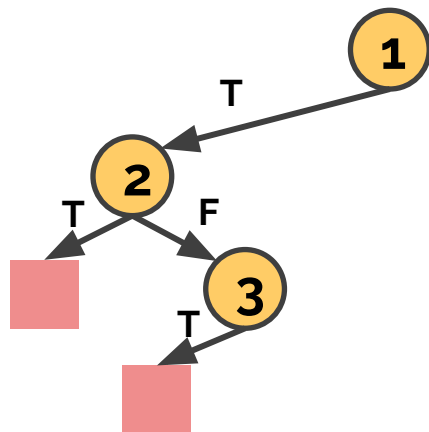
$$(\bar{1} \vee \bar{2})$$

$$(\bar{1} \vee 2 \vee \bar{3}) \quad \text{Conflict!}$$

$$(3 \vee \bar{4} \vee \bar{5})$$

$$(3 \vee 4 \vee \bar{5})$$

Steps



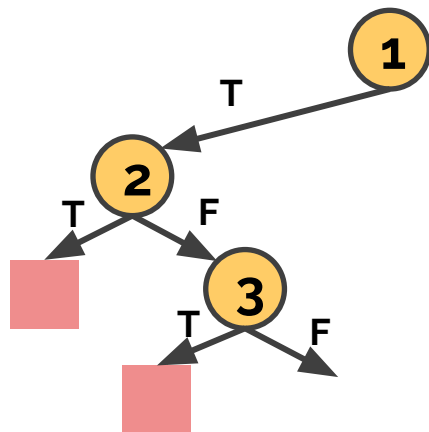
1	2	3	4	5
T	F	T		



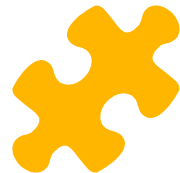
Example: 1 Watched Literal

$(\bar{1} \vee \bar{2})$
 $(\bar{1} \vee 2 \vee \bar{3})$
 $(3 \vee \bar{4} \vee \bar{5})$
 $(3 \vee 4 \vee \bar{5})$

Steps



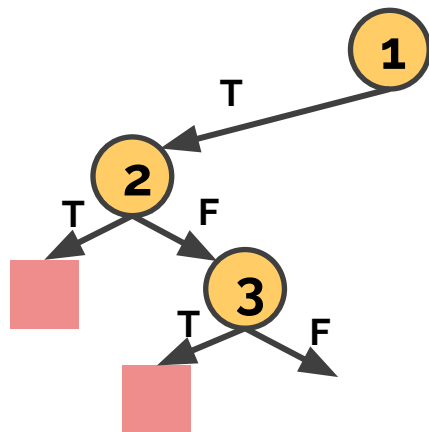
1	2	3	4	5
T	F	F		



Example: 1 Watched Literal

$(\bar{1} \vee \bar{2})$
 $(\bar{1} \vee 2 \vee \bar{3})$
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 $(3 \vee \bar{4} \vee \bar{5})$

Steps



1	2	3	4	5
T	F	F		

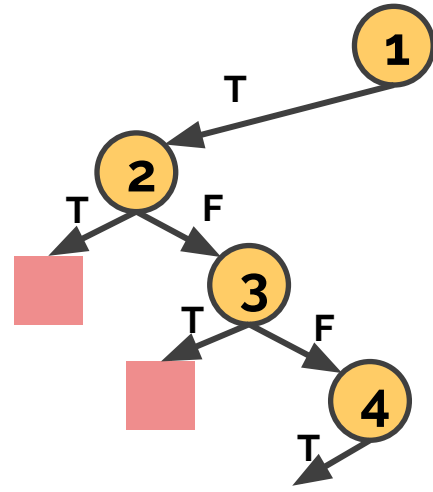


Example: 1 Watched Literal

- $(\bar{1} \vee \bar{2})$
- $(\bar{1} \vee 2 \vee \bar{3})$
- $(3 \vee \bar{4} \vee \bar{5})$
- $(3 \vee 4 \vee \bar{5})$

1	2	3	4	5
T	F	F	T	

Steps



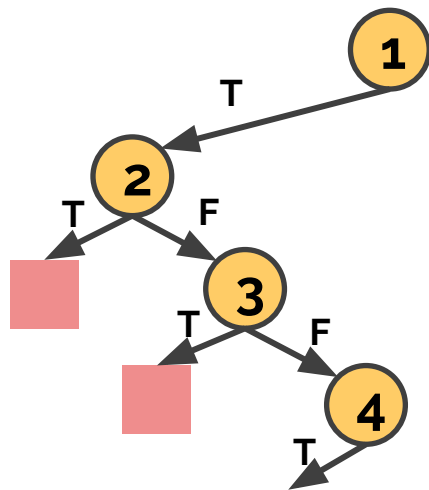


Example: 1 Watched Literal

- $(\bar{1} \vee \bar{2})$
- $(\bar{1} \vee 2 \vee \bar{3})$
- $(3 \vee \bar{4} \vee \bar{5})$
- $(3 \vee 4 \vee \bar{5})$

1	2	3	4	5
T	F	F	T	

Steps



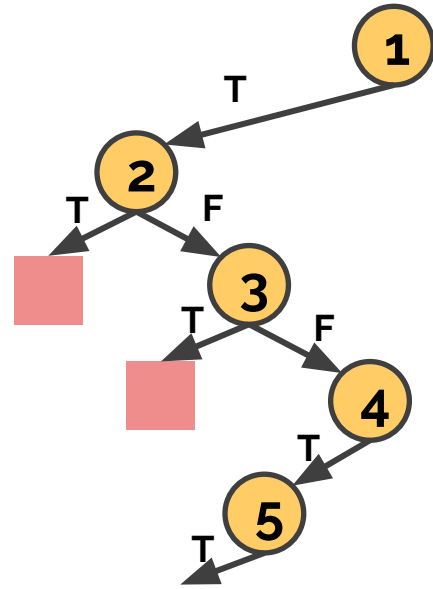


Example: 1 Watched Literal

- $(\bar{1} \vee \bar{2})$
- $(\bar{1} \vee 2 \vee \bar{3})$
- $(3 \vee \bar{4} \vee \bar{5})$
- $(3 \vee 4 \vee \bar{5})$

1	2	3	4	5
T	F	F	T	T

Steps





Example: 1 Watched Literal

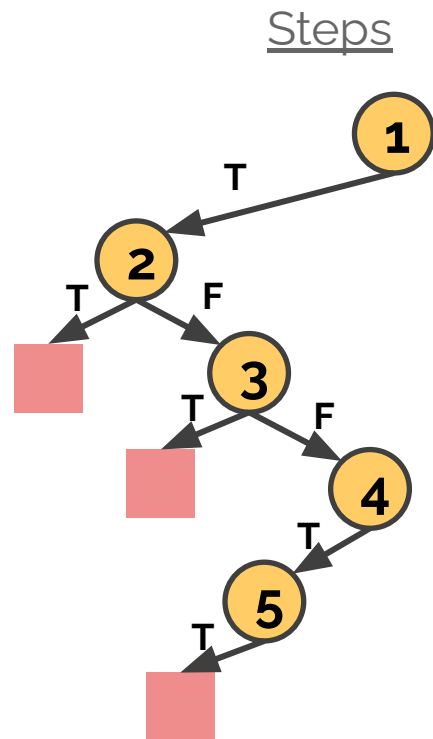
$$(\bar{1} \vee \bar{2})$$

$$(\bar{1} \vee 2 \vee \bar{3})$$

$$(3 \vee \bar{4} \vee \bar{5})$$
 Conflict!

$$(3 \vee 4 \vee \bar{5})$$

1	2	3	4	5
T	F	F	T	T



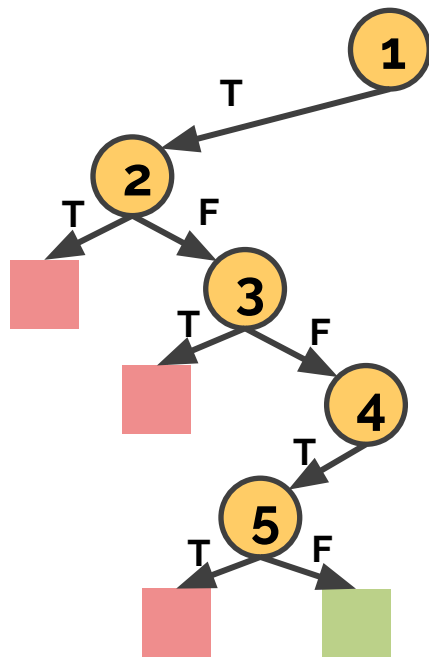


Example: 1 Watched Literal

$(\bar{1} \vee \bar{2})$
 $(\bar{1} \vee 2 \vee \bar{3})$
 $(3 \vee \bar{4} \vee \bar{5})$
 $(3 \vee 4 \vee \bar{5})$

1	2	3	4	5
T	F	F	T	F

Steps



Find a *satisfying assignment* for the following formula:

$$\varphi = (x_1 \vee \overline{x_2} \vee \overline{x_3} \vee x_4) \wedge (\overline{x_1} \vee \overline{x_3}) \wedge (x_3) \wedge (x_4 \vee \overline{x_5} \vee \overline{x_7}) \wedge (x_3 \vee x_5 \vee x_6 \vee \overline{x_7}) \wedge (\overline{x_5} \vee \overline{x_6})$$

Find a *satisfying assignment* for the following formula:

$$\varphi = (x_1 \vee \overline{x_2} \vee \overline{x_3} \vee x_4) \wedge (\overline{x_1} \vee \overline{x_3}) \wedge (x_3) \wedge (x_4 \vee \overline{x_5} \vee \overline{x_7}) \wedge (x_3 \vee x_5 \vee x_6 \vee \overline{x_7}) \wedge (\overline{x_5} \vee \overline{x_6})$$

$$x_1 = \text{FALSE} \quad x_2 = \text{FALSE} \quad x_3 = \text{TRUE}$$

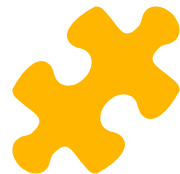
$$x_4 = \text{TRUE} \quad x_5 = \text{FALSE} \quad x_6 = \text{TRUE} \quad x_7 = \text{TRUE}$$

Unit Propagation (UP)

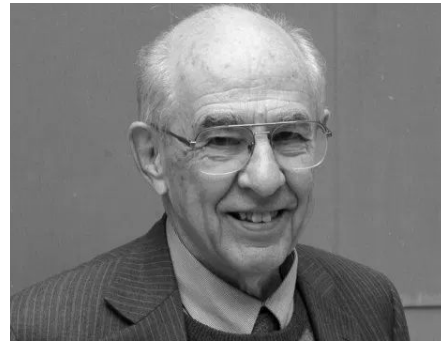


- A **unit clause** is a clause containing only one literal
- **Unit propagation rule:** for any unit clause $\{\ell\}$, we must set $\ell = T$
- Applying unit propagation can massively speed up the backtracking algorithm in practice
 - Combining with the splitting rule can lead to a “domino effect” of cascading unit propagation

The DPLL Algorithm



- Davis-Putnam-Logemann-Loveland (1962)
- Improved upon naive backtracking (search) with unit propagation (inference)
- Still the basic algorithm behind most state-of-the-art SAT solvers today!



DPLL (Pseudocode)



```
dpll( $\varphi$ ):  
  if  $\varphi = \emptyset$ : return TRUE  
  if  $\epsilon \in \varphi$ : return FALSE  
  if  $\varphi$  contains unit clause  $\{\ell\}$ :  
    return dpll( $\varphi|\ell$ )  
  let  $x = \text{pick\_variable}(\varphi)$   
  return dpll( $\varphi|x$ ) OR dpll( $\varphi|\bar{x}$ )
```



Example: DPLL

Steps

$$\left(\bar{1} \vee \bar{2} \right)$$

$$\left(\bar{1} \vee 2 \right)$$

$$\left(1 \vee \bar{2} \vee 3 \right)$$

$$\left(1 \vee 2 \vee \bar{4} \right)$$

1	2	3	4



Example: DPLL

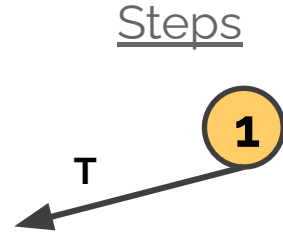
$$\left(\bar{1} \vee \bar{2} \right) \quad \text{Unit!}$$

$$\left(\bar{1} \vee 2 \right)$$

$$\left(1 \vee \bar{2} \vee 3 \right)$$

$$\left(1 \vee 2 \vee \bar{4} \right)$$

1	2	3	4
T			





Example: DPLL

$$\left(\overline{1} \vee \overline{2} \right)$$

$$\left(\overline{1} \vee 2 \right)$$

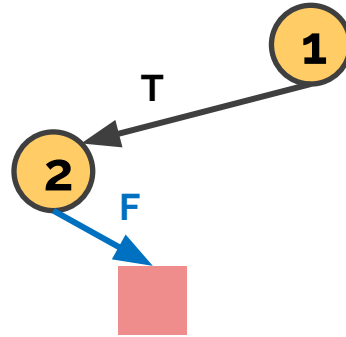
Conflict!

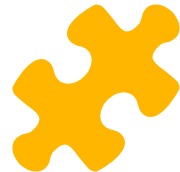
$$\left(1 \vee \overline{2} \vee 3 \right)$$

$$\left(1 \vee 2 \vee \overline{4} \right)$$

1	2	3	4
T	F		

Steps





Example: DPLL

$$\left(\bar{1} \vee \bar{2} \right)$$

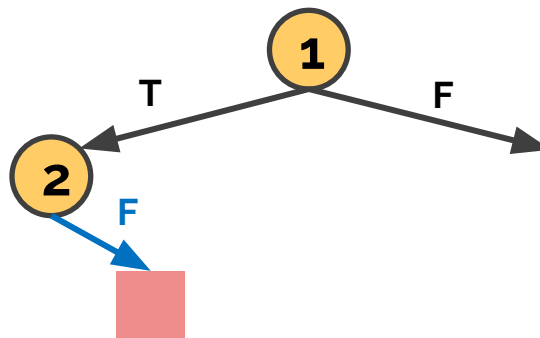
$$\left(\bar{1} \vee 2 \right)$$

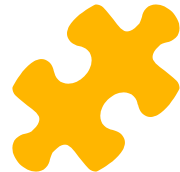
$$\left(1 \vee \bar{2} \vee 3 \right)$$

$$\left(1 \vee 2 \vee \bar{4} \right)$$

1	2	3	4
F			

Steps





Example: DPLL

$$\left(\bar{1} \vee \bar{2} \right)$$

$$\left(\bar{1} \vee 2 \right)$$

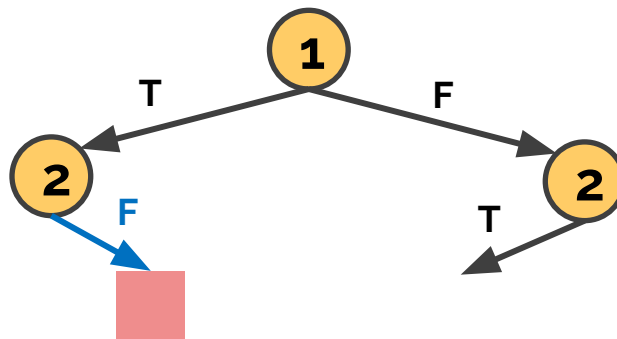
$$\left(1 \vee \bar{2} \vee 3 \right)$$

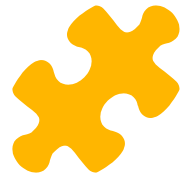
$$\left(1 \vee 2 \vee \bar{4} \right)$$

Unit!

1	2	3	4
F	T		

Steps





Example: DPLL

$$\left(\bar{1} \vee \bar{2} \right)$$

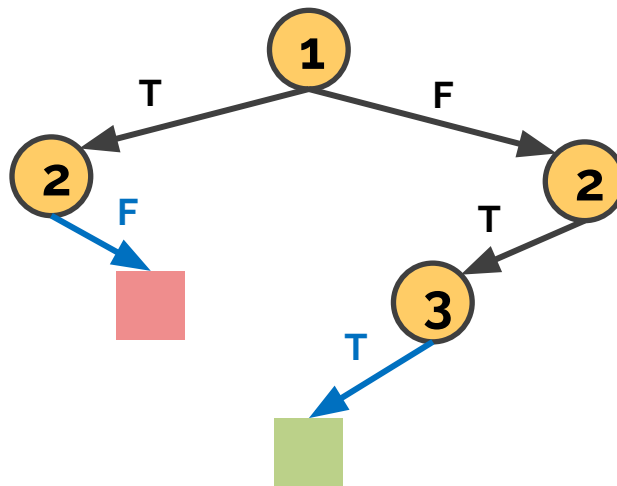
$$\left(\bar{1} \vee 2 \right)$$

$$\left(1 \vee \bar{2} \vee 3 \right)$$

$$\left(1 \vee 2 \vee \bar{4} \right)$$

1	2	3	4
F	T	T	

Steps



Engineering Matters



- Since the main DPLL subroutine might run exponentially many times, every speedup counts
- DPLL spends by far the most time on UP
 - How can we speed this up?
- Although DPLL has a natural recursive formulation, recursion is slow — lots of overhead
 - We can make DPLL **iterative** using a stack



2 Watched Literals (2WL)

- **Key observation:** a clause can only be unsatisfied or unit if it has at most one non-False literal
 - Optimize unit propagation: only visit those clauses
- Each clause “watches” two literals and maintains watching **invariant:** the watched literals are not False, unless the clause is satisfied
 - If a watched literal becomes False, watch another
- If can't maintain invariant, clause is unit (can propagate)



2 Watched Literals (2WL)

- Still use watchlists (list of all clauses watching each lit)
- Best part: since backtracking only unassigns variables, it can never break the 2WL invariant
 - Don't need to update watchlists

$$\left(\overline{\mathbf{1}} \vee \mathbf{2} \vee \overline{\mathbf{3}} \right) \xrightarrow{\text{Set 1} = T} \left(\overline{\mathbf{1}} \vee \mathbf{2} \vee \overline{\mathbf{3}} \right) \xrightarrow{\text{Set 2} = F} \left(\overline{\mathbf{1}} \vee \mathbf{2} \vee \overline{\mathbf{3}} \right)$$

Unit!



How should we branch?

- Order of assigning variables greatly affects runtime
- Want to find a satisfying assignment quicker and find conflicts (rule out bad assignments) quicker
- **Ex:** $\{1\bar{2}34, \bar{1}23, 12\bar{3}5, 23\bar{5}, 3\bar{4}5, \dots, 6\bar{7}, \bar{6}7, 6\bar{7}, \bar{6}\bar{7}\}$
 - If we assign 6 first, then we can find conflicts right away



Decision Heuristics

- **Static heuristics:** variable ordering fixed at the start
- **Dynamic heuristics:** variable ordering is updated as the solver runs
 - More effective, but also more expensive
- Basic examples of decision heuristics:
 - Random ordering
 - Most-frequent static ordering
 - Most-frequent dynamic ordering

Stay Wise



“Intelligence is knowing it is a one-way street, wisdom is still looking both ways before crossing.”

References



A. Biere, *Handbook of satisfiability*. Amsterdam: IOS Press, 2009.

N. Eén and N. Sörensson, "An Extensible SAT-solver," *Theory and Applications of Satisfiability Testing Lecture Notes in Computer Science*, pp. 502–518, 2004.